Applications of Cloud Computing in Intelligent Vehicles: A Survey

Luis Hernandez Universidad del Bío-Bío in Concepción. Mohammad Hassan

hssnn2050@gmail.com

Vatsal P Shukla vatsal813@gmail.com

RECEIVED 7 September 2022 REVISED 6 October 2022

ACCEPTED FOR PUBLICATION 2 February 2023

PUBLISHED 10 February 2023

Keywords:

- 1. Intelligent vehicles
- 2. Cloud computing
- 3. Data storage and processing
- 4. Vehicle-to-vehicle communication
- 5. Autonomous driving technologies

Abstract

The rising popularity of intelligent vehicles has led to a significant surge in the volume of data that these vehicles generate. As a result, there is an urgent need for effective and efficient data storage, processing, and analysis techniques to support the development of advanced intelligent vehicle systems. Cloud computing has emerged as a promising solution to address the challenges associated with the large volume of data generated by intelligent vehicles. This research paper explores the various applications of cloud computing in intelligent vehicles. The study begins by providing an overview of the intelligent vehicle architecture and the role of cloud computing in this architecture. It then proceeds to explore the different types of cloud computing services and their relevance to intelligent vehicles. Cloud computing is revolutionizing the automotive industry by offering a range of applications that enhance the efficiency, safety, and entertainment of intelligent vehicles. Real-time traffic updates are one such application that can help vehicles adjust their routes to avoid congestion and save time. Additionally, cloud computing can be used for predictive maintenance by analyzing data from intelligent vehicles to predict when a vehicle will need maintenance, reducing downtime and increasing efficiency. Vehicle-to-vehicle communication is another benefit of cloud computing, enabling vehicles to communicate with each other and share information about traffic conditions, weather, and other factors that could affect their journey. Fleet management is also made easier with cloud computing, as it allows for tracking vehicle locations, managing maintenance schedules, and optimizing routes. Furthermore, cloud computing can support the development of autonomous driving technologies by providing the processing power and data storage necessary to analyze vast amounts of data in real-time. Finally, cloud computing can offer infotainment services to passengers in intelligent vehicles, including access to music, movies, and other entertainment options. The study identifies the applications of using cloud computing in intelligent vehicles and highlights the need for further research in this area. The findings of this study have implications for the automotive industry, policymakers, and researchers who are interested in the use of cloud computing in intelligent vehicles.

Introduction

Intelligent vehicles are becoming increasingly prevalent due to advancements in technology. They rely on a variety of sensors, such as lidar, radar, and cameras, to perceive their surroundings and make decisions based on that information. These sensors can detect obstacles, pedestrians, other vehicles, and road conditions, enabling the vehicle to navigate safely and efficiently. The software running in the car processes the sensor data to generate a virtual representation of the environment, which is used to control the vehicle's movements. Additionally, communication technologies enable intelligent vehicles to exchange information with other vehicles and infrastructure, further enhancing their capabilities [1-3].

One of the most significant benefits of intelligent vehicles is their potential to improve safety on the road. Autonomous vehicles are designed to operate within a set of rules and guidelines, and they can react more quickly than human drivers in dangerous situations. They can also monitor their surroundings in all directions simultaneously, eliminating blind spots and reducing the risk of accidents. Furthermore, they can communicate with each other, alerting nearby vehicles of potential hazards and coordinating their movements to avoid collisions. By eliminating human error, which is responsible for the vast majority of traffic accidents, intelligent vehicles have the potential to save thousands of lives each year.

In addition to improving safety, intelligent vehicles have the potential to reduce traffic congestion and improve mobility. They can operate more efficiently than human-driven vehicles, accelerating and decelerating smoothly and maintaining a safe following distance. They can also navigate through traffic more effectively, making use of all available space on the road and avoiding unnecessary delays. This increased efficiency can lead to reduced travel times and lower fuel consumption, which can help alleviate traffic congestion and reduce greenhouse gas emissions [4]. Overall, intelligent vehicles have the potential to transform the way we travel, making it faster, safer, and more sustainable.

Intelligent vehicles are equipped with a variety of advanced sensors, including cameras, radar, and lidar, that enable them to perceive their surroundings with far greater accuracy than human drivers. This allows them to detect and respond to potential hazards much more quickly, and to make decisions based on a broader range of data. For example, an intelligent vehicle can detect an object in its path even if it is obscured by another vehicle or a bend in the road. It can also detect and respond to sudden changes in road conditions, such as a patch of ice or a pothole.

Moreover, intelligent vehicles are programmed to adhere strictly to traffic laws and safety regulations. They do not become distracted, tired, or impaired like human drivers, and they do not engage in risky behaviors such as speeding or tailgating. As a result, they are less likely to cause accidents than human drivers. Additionally, because they can communicate with each other and with traffic infrastructure, they can operate in a coordinated and efficient manner, further reducing the risk of accidents [5], [6]. The potential of intelligent vehicles to reduce accidents and save lives is significant. By eliminating human error and adhering strictly to traffic laws and safety regulations, intelligent vehicles offer a safer, more efficient alternative to traditional human-driven vehicles. As technology continues to improve, it is likely that we will see more and more intelligent vehicles on our roads, making our highways safer and more efficient than ever before.

Cloud computing refers to the delivery of computing services over the internet. It allows users to access a wide range of computing resources, including servers, storage, databases, software, and analytics tools, without the need for physical infrastructure. Cloud computing provides a flexible and scalable way to manage IT resources, enabling businesses to rapidly scale up or down their computing infrastructure as their needs change. This makes it particularly valuable for organizations with unpredictable or fluctuating computing needs.

Cloud computing also offers a number of other benefits to users, including increased efficiency, lower costs, and improved security [7-9]. By moving their computing resources to the cloud, organizations can reduce their reliance on expensive on-premises hardware, software, and IT staff. This can lead to significant cost savings over time, as well as increased agility and responsiveness to changing business needs. Cloud providers also typically offer robust security measures and data backup capabilities, helping to ensure that data is safe and accessible in the event of an outage or disaster [10-13].

Applications of cloud computing in intelligent vehicles

Cloud computing has several applications in intelligent vehicles that can enhance their performance and safety. One such application is real-time traffic updates. Cloud computing can provide real-time traffic updates to intelligent vehicles, allowing them to adjust their routes to avoid congestion and save time [14]. This feature can benefit drivers, passengers, and logistics companies by reducing travel time and increasing efficiency.

Another application of cloud computing in intelligent vehicles is predictive maintenance. By analyzing data from intelligent vehicles, cloud computing can predict when a vehicle will need maintenance, reducing downtime and increasing efficiency. This application can benefit fleet managers and logistics companies by reducing maintenance costs and improving vehicle uptime.



Cloud computing can also enable vehicle-to-vehicle communication. Intelligent vehicles can share information with each other, such as traffic conditions, weather, and other factors that could affect their journey. This feature can enhance safety by providing drivers with real-time information that can help them avoid accidents and make better decisions while on the road.

Cloud computing can also be used for fleet management. It can help fleet managers track the location of their vehicles, manage their maintenance schedules, and optimize their routes. This feature can benefit logistics companies by improving fleet efficiency and reducing costs.

Another significant application of cloud computing in intelligent vehicles is autonomous driving. Cloud computing can support the development of autonomous driving technologies by providing the processing power and data storage needed to analyze vast amounts of data in realtime. This feature can enhance safety by reducing human error and improving vehicle efficiency. Finally, cloud computing can provide infotainment services to passengers in intelligent vehicles, including access to music, movies, and other entertainment options. This feature can enhance the passenger experience and make long journeys more enjoyable [15].

Real-time traffic updates

Cloud computing has become a revolutionary technology that has transformed the way businesses operate. One of its most significant applications is in providing real-time traffic updates to intelligent vehicles [16-17]. By leveraging the power of the cloud, intelligent vehicles can now adjust their routes in real-time to avoid congestion and save time.

Real-time traffic updates are essential for intelligent vehicles because they enable them to make informed decisions about the best routes to take. This is achieved by using sensors and cameras to monitor the traffic situation and collect data in real-time. The data is then processed and analyzed by cloud-based algorithms that can predict traffic patterns and identify potential bottlenecks.

The cloud-based algorithms are highly advanced and can provide accurate predictions of traffic patterns. They use machine learning and artificial intelligence techniques to analyze large amounts of data from various sources, including traffic sensors, GPS devices, and social media. This enables the algorithms to identify patterns and trends in the data and make accurate predictions about future traffic patterns.

Intelligent vehicles can use these predictions to adjust their routes in real-time to avoid congestion and save time. For example, if the algorithm predicts that there will be heavy traffic on a particular road, the vehicle can choose an alternative route that is less congested. This can significantly reduce travel times and improve the overall efficiency of the transportation system. The benefits of real-time traffic updates extend beyond just saving time. They can also improve road safety by reducing the number of accidents caused by congestion. When traffic is flowing smoothly, there are fewer opportunities for accidents to occur. Real-time traffic updates can also help to reduce carbon emissions by reducing the time vehicles spend on the road.

Cloud computing has made it possible to provide real-time traffic updates to a wide range of intelligent vehicles, including cars, buses, and trucks. This is because cloud-based systems are highly scalable and can handle large amounts of data from multiple sources. This means that the system can provide real-time traffic updates to a large number of vehicles simultaneously, without any degradation in performance.

Furthermore, cloud-based systems are highly secure and reliable. They use advanced encryption and security protocols to protect data from unauthorized access and ensure the integrity of the system [19]. This means that real-time traffic updates can be provided to intelligent vehicles with a high degree of confidence that the data is accurate and secure.

Real-time traffic updates are already being used in several cities around the world. For example, the City of Los Angeles has deployed a cloud-based system that provides real-time traffic updates to its fleet of intelligent vehicles. The system uses data from traffic sensors, GPS devices, and social media to provide accurate and up-to-date information about traffic conditions.

In conclusion, real-time traffic updates are a game-changer for the transportation industry. By leveraging the power of cloud computing, intelligent vehicles can now adjust their routes in real-time to avoid congestion and save time. This technology has the potential to transform the way we travel and make our roads safer, more efficient, and more sustainable. With continued advancements in cloud-based technologies, we can expect to see even more exciting developments in this area in the coming years [20-23].

Predictive maintenance

Predictive maintenance has emerged as one of the most promising applications of cloud computing in the transportation industry. By analyzing data from intelligent vehicles, cloud-based systems can predict when a vehicle will need maintenance, reducing downtime and increasing efficiency [24], [25].

Traditionally, maintenance has been carried out on a reactive basis, with repairs being made after a vehicle breaks down. This approach can be costly and time-consuming, as it often involves taking the vehicle out of service and repairing it. Predictive maintenance, on the other hand, involves analyzing data from the vehicle to predict when maintenance will be required, enabling repairs to be made before a breakdown occurs.

Intelligent vehicles are equipped with a wide range of sensors and monitoring systems that generate vast amounts of data. This data can be collected and analyzed by cloud-based systems using machine learning and artificial intelligence techniques. The algorithms used in predictive maintenance can identify patterns and trends in the data that are indicative of potential maintenance issues [26-28].

For example, if a sensor indicates that a particular component is operating at a temperature that is higher than normal, this could indicate that the component is wearing out and may need to be replaced soon. By analyzing data from multiple sensors, cloud-based systems can build a more comprehensive picture of the vehicle's condition and predict when maintenance will be required.

Predictive maintenance offers several benefits to the transportation industry. First and foremost, it reduces downtime by enabling repairs to be made before a breakdown occurs. This means that vehicles can be kept on the road for longer, improving efficiency and reducing costs [29]. Secondly, predictive maintenance can extend the life of vehicle components. By identifying potential issues early, repairs can be made before the component fails completely, reducing the risk of damage to other parts of the vehicle. Finally, predictive maintenance can improve safety. Vehicles that are well-maintained are less likely to experience a breakdown, reducing the risk of accidents and injuries.

Cloud computing is the key enabler of predictive maintenance in the transportation industry. Cloud-based systems are highly scalable and can handle vast amounts of data from multiple sources. This means that data from intelligent vehicles can be collected and analyzed in realtime, providing up-to-date information about the vehicle's condition. Furthermore, cloud-based systems can be accessed remotely, enabling maintenance teams to monitor the condition of vehicles from anywhere in the world. This can be particularly useful for fleets that operate in multiple locations, as it enables maintenance teams to prioritize repairs based on the most critical issues. Cloud-based systems are also highly secure and reliable. They use advanced encryption and security protocols to protect data from unauthorized access and ensure the integrity of the system. This means that maintenance teams can have confidence in the accuracy of the data and make informed decisions about when and where to carry out repairs. By leveraging the power of cloud computing, intelligent vehicles can now be maintained on a predictive basis, reducing downtime, improving efficiency, and increasing safety. With continued advancements in cloud-based technologies, we can expect to see even more exciting developments in this area in the coming years [31-33].

Vehicle-to-vehicle communication

Vehicle-to-vehicle (V2V) communication is an emerging technology that promises to revolutionize the transportation industry. By enabling intelligent vehicles to communicate with each other, V2V can improve safety, reduce congestion, and increase efficiency. Cloud computing plays a crucial role in enabling V2V communication by providing a platform for the collection, storage, and processing of data.

V2V communication involves the exchange of information between vehicles in real-time. This information can include data on traffic conditions, weather, road hazards, and other factors that could affect the safety or efficiency of a journey. By sharing this information, intelligent vehicles can make better-informed decisions about their route, speed, and driving behavior.

Cloud computing is essential to V2V communication because it provides a platform for the collection, storage, and processing of data. Intelligent vehicles generate vast amounts of data, including sensor readings, GPS data, and video footage. Cloud-based systems can collect and process this data in real-time, providing up-to-date information on traffic conditions and other factors.

Cloud-based systems can also store historical data, enabling patterns and trends to be identified over time. This can be useful for predicting traffic congestion, identifying accident hotspots, and optimizing traffic flow. By analyzing historical data, cloud-based systems can also identify areas where road infrastructure improvements may be required, such as the installation of traffic lights or roundabouts.

One of the main benefits of V2V communication is improved safety. By sharing information about road conditions and hazards, intelligent vehicles can make better-informed decisions about their driving behavior. For example, if a vehicle ahead suddenly brakes, V2V communication can alert the following vehicles, enabling them to slow down and avoid a collision. V2V communication can also improve efficiency by reducing congestion. By sharing information on traffic conditions and road closures, intelligent vehicles can avoid congestion hotspots and take alternative routes. This can reduce travel time, fuel consumption, and emissions. Cloud computing is also critical to the security of V2V communication. Cloud-based systems can use advanced encryption and security protocols to protect data from unauthorized access [35-38]. This is essential to ensure that the information exchanged between vehicles is accurate and reliable.

Vehicular Cloud Networks (VCN) represent an application of cloud computing that integrates cloud and Vehicular Ad-hoc Network (VANET) technologies. Vehicular Ad-hoc Network (VANET) refers to a specialized form of ad-hoc network that enables vehicles to establish temporary and self-configuring communication links with one another, forming a dynamic

network on-the-go [39]. In a VANET, vehicles act as mobile nodes, equipped with wireless communication capabilities, such as Wi-Fi or Dedicated Short-Range Communications (DSRC), to facilitate direct communication with nearby vehicles and roadside infrastructure.

The primary objective of VANET is to enhance road safety, traffic efficiency, and overall driving experience through the exchange of real-time information between vehicles and infrastructure [40]. It allows vehicles to share important data, such as their current speed, position, acceleration, braking status, and other critical information [41]. This data can be utilized to implement various applications and services aimed at improving road safety and traffic flow. While VANETs are highly dynamic network, reliability for VANETs plays a very important role in stability of the network [42],[43]. VCN emerges as a promising solution to address the challenges of real-time data processing and efficient communication in vehicular environments. The VCN ecosystem consists of three fundamental clouds, each playing a pivotal role in enhancing the overall functionality of the system.

The first component, the Vehicular Cloud, forms the heart of the network and is primarily composed of vehicles on the road. These vehicles act as mobile nodes in the VANET, creating a dynamic network that facilitates data sharing and collaboration among nearby vehicles. The Vehicular Cloud leverages its collective computing power and storage capacity to process and disseminate critical information, such as traffic conditions, road hazards, and weather updates.

The second component in the VCN architecture is the Infrastructure Cloud. This cloud layer encompasses fixed roadside units, traffic management centers, and other stationary elements within the transportation infrastructure. The Infrastructure Cloud provides a stable and reliable backbone for VCN, supporting the communication between Vehicular Cloud and the third component, the traditional IT Cloud. With its robust data centers and computational capabilities, the Infrastructure Cloud facilitates resource-intensive tasks, such as data analytics, predictive maintenance, and AI-driven decision-making.

Lastly, the traditional IT Cloud serves as the global cloud infrastructure that integrates with the Vehicular Cloud and Infrastructure Cloud. It connects VCN to the broader internet and other cloud services, allowing data exchange and access to a plethora of cloud-based applications. The traditional IT Cloud enhances the scalability and flexibility of VCN, enabling the implementation of diverse services, such as infotainment for passengers, vehicle diagnostics, and remote software updates. By merging cloud computing paradigms with vehicular networks, the traditional IT Cloud brings forth a new form of intelligent transportation.

Fleet management

Fleet management is a critical function in many industries, from logistics and delivery to public transportation and emergency services. Cloud computing can help organizations manage their fleets of intelligent vehicles more efficiently and effectively by providing real-time data on vehicle location, performance, and maintenance needs. Cloud-based fleet management systems use GPS tracking and other sensors to monitor vehicle location and performance in real-time. This information is transmitted to the cloud, where it can be analyzed to provide insights into driver behavior, fuel consumption, and maintenance needs. By tracking vehicle location and performance in real-time, cloud-based fleet management systems can optimize routes, reducing travel time and fuel consumption.

Cloud-based fleet management systems can also be used to manage maintenance schedules for intelligent vehicles. By collecting data on vehicle performance and maintenance needs, cloud-based systems can predict when a vehicle is likely to need maintenance, reducing downtime

and increasing efficiency. This can be especially important for organizations that rely on their vehicles for critical operations, such as emergency services or transportation providers.

Cloud-based fleet management systems can also provide real-time alerts for vehicle issues, such as low fuel or engine problems. This enables fleet managers to respond quickly to issues before they become more serious, reducing the risk of breakdowns and improving the overall reliability of the fleet.

Another key benefit of cloud-based fleet management systems is the ability to optimize routes in real-time. By analyzing traffic patterns, road closures, and other factors, cloud-based systems can suggest alternative routes that may be more efficient, reducing travel time and fuel consumption. This can also help organizations meet tight delivery schedules or respond quickly to emergency situations.

Cloud-based fleet management systems can also provide data analytics and reporting capabilities, allowing fleet managers to analyze vehicle performance over time and identify areas for improvement. This can include driver behavior, fuel consumption, and maintenance needs [44-46]. By identifying areas for improvement, organizations can optimize their fleets and reduce costs over time. Cloud-based fleet management systems can also be integrated with other technologies, such as telematics and electronic logging devices (ELDs). This enables fleet managers to collect additional data on vehicle performance, such as driver hours and engine performance. By integrating these technologies, organizations can optimize their fleets even further and reduce the risk of compliance violations. Finally, cloud-based fleet management systems can be accessed from anywhere, enabling fleet managers to monitor their fleets remotely. This can be especially important for organizations with multiple locations or fleets that operate in different regions. By accessing real-time data on vehicle location and performance, fleet managers can make informed decisions about their operations from anywhere in the world. Cloud computing can be used to manage fleets of intelligent vehicles more efficiently and effectively. Cloud-based fleet management systems provide real-time data on vehicle location, performance, and maintenance needs, enabling organizations to optimize their fleets and reduce costs over time. With continued advancements in cloud-based technologies, we can expect to see even more exciting developments in fleet management in the coming years.

Autonomous driving

Autonomous driving is one of the most exciting and rapidly developing areas of intelligent vehicle technology. Autonomous vehicles use a variety of sensors, including cameras, lidar, and radar, to gather data about their environment and make decisions about how to navigate it. However, processing and analyzing this data in real-time requires enormous amounts of computing power and data storage, which can be provided by cloud computing.

Cloud computing can support the development of autonomous driving technologies in several ways. First, cloud-based systems can provide the massive amounts of computing power needed to process and analyze the vast quantities of data generated by autonomous vehicles. This includes data from sensors, as well as data from other sources, such as weather and traffic conditions [47-50].

Second, cloud-based systems can provide the data storage needed to store and manage the enormous amounts of data generated by autonomous vehicles. This includes not only data from sensors, but also data from other sources, such as maps, road signs, and traffic signals.

Third, cloud-based systems can provide the connectivity needed to enable autonomous vehicles to communicate with other vehicles and with infrastructure, such as traffic lights and road signs. This enables autonomous vehicles to gather real-time information about their environment and make decisions based on that information.

Fourth, cloud-based systems can provide the machine learning and artificial intelligence algorithms needed to analyze and interpret the data generated by autonomous vehicles. This includes algorithms for object detection, lane detection, and other critical functions needed for autonomous driving.

Finally, cloud-based systems can provide the testing and validation tools needed to ensure that autonomous driving technologies are safe and reliable. This includes simulating real-world scenarios, testing different algorithms and configurations, and analyzing data from real-world tests.

Overall, cloud computing can support the development of autonomous driving technologies in many ways. By providing the processing power, data storage, connectivity, and machine learning capabilities needed to analyze vast amounts of data in real-time, cloud-based systems can enable the development of safer, more reliable, and more efficient autonomous vehicles [51-53]. As the technology continues to advance, we can expect to see even more exciting developments in autonomous driving enabled by cloud computing.

Infotainment services

Intelligent vehicles are not just about getting from one point to another but also providing an enjoyable experience to passengers during their journey. Infotainment systems play a critical role in providing passengers with an enjoyable ride experience. Cloud computing can enhance the capabilities of infotainment systems in intelligent vehicles by providing access to a wide range of services, including music, movies, and other entertainment options.

One of the primary advantages of using cloud computing for infotainment services is the ability to provide a vast library of content to passengers. With cloud-based systems, passengers can access a virtually unlimited selection of music, movies, and other forms of entertainment, all of which can be streamed directly to the vehicle's infotainment system. Cloud-based services can also provide personalized recommendations based on the passenger's previous preferences and listening habits, providing a more customized entertainment experience.

In addition to providing access to entertainment content, cloud computing can also enhance the safety and convenience of infotainment systems. For example, cloud-based navigation systems can provide real-time updates on traffic and road conditions, allowing passengers to avoid congestion and arrive at their destination more quickly. Cloud-based voice recognition systems can also enable hands-free operation of the infotainment system, reducing distractions for the driver and improving safety.

Cloud computing can also provide a platform for new and innovative infotainment services. For example, some automakers are experimenting with augmented reality (AR) technology to provide passengers with a more immersive and interactive entertainment experience. Cloud-based AR systems can provide passengers with information about their surroundings in real-time, allowing them to learn about landmarks, historical sites, and other points of interest during their journey.

Another example of innovative infotainment services enabled by cloud computing is gamification. Automakers are experimenting with gamification features that allow passengers

to compete against one another, earn rewards, and unlock achievements during their journey. Cloud-based systems can provide the processing power and data storage needed to support these gamification features, making them more engaging and enjoyable for passengers [54-56].

Overall, cloud computing can significantly enhance the capabilities of infotainment systems in intelligent vehicles. By providing access to a vast library of content, real-time updates on traffic and road conditions, hands-free operation, and new and innovative services, cloud-based systems can provide passengers with a more enjoyable and engaging ride experience. As the technology continues to evolve, we can expect to see even more exciting developments in infotainment services enabled by cloud computing.

Conclusion

Cloud computing has revolutionized the way we interact with technology. Intelligent vehicles have also benefited from this innovation, but the use of cloud computing in this field has its limitations. These limitations can affect the performance and reliability of intelligent vehicles.

One of the primary limitations of cloud computing in intelligent vehicles is latency. Latency refers to the time it takes for data to travel from the vehicle to the cloud server and back. For intelligent vehicles, this delay can have serious consequences, particularly in safety-critical situations. The delay can affect the performance of driver assistance systems, such as collision avoidance systems, as they rely on real-time data to function properly. Even a small delay in data transmission can significantly impact the accuracy of these systems, potentially leading to accidents.

Another limitation of cloud computing in intelligent vehicles is the dependency on network connectivity. Intelligent vehicles require a reliable and consistent network connection to access cloud services. However, network connectivity can be disrupted due to factors such as network congestion, interference, or signal loss. This dependency on network connectivity can cause downtime, data loss, and system failure, which can significantly impact the reliability and availability of the intelligent vehicle systems.

Data privacy and security is another significant limitation of cloud computing in intelligent vehicles. Intelligent vehicles collect and transmit a massive amount of sensitive data to the cloud servers, such as location, speed, and driving behavior. This data can be intercepted or stolen by cybercriminals, leading to identity theft, fraud, or even physical harm. As a result, there are concerns over the safety and privacy of this data, and regulatory measures are being put in place to ensure that the data is protected.

The cost of cloud computing services is also a limitation in intelligent vehicles. Cloud computing services require high-speed internet connectivity, robust infrastructure, and skilled professionals to manage the systems. These requirements can increase the cost of implementing and maintaining cloud computing services in intelligent vehicles. As a result, it can be challenging to implement cloud computing services in low-cost and budget vehicles, limiting their adoption [57], [58].

These limitations, such as latency, network dependency, data privacy, and cost, can impact the performance, reliability, and availability of intelligent vehicle systems. As the use of cloud computing in intelligent vehicles continues to grow, addressing these limitations will be crucial to ensure the safe and efficient operation of these vehicles.

Cloud computing has emerged as a game-changer in the automotive industry, with numerous benefits for intelligent vehicles. However, the future of cloud computing in intelligent vehicles

is still evolving, and there are several exciting developments. Firstly, the use of cloud computing is expected to enhance the functionality and capabilities of intelligent vehicles. Cloud computing enables vehicles to access real-time data from various sources, including other vehicles, road infrastructure, and weather stations. This data can be used to optimize the performance of the vehicle, improve safety, and enhance the driving experience. For example, cloud computing can enable intelligent vehicles to adjust their speed based on real-time traffic conditions, reducing congestion and improving fuel efficiency.

Secondly, the integration of cloud computing and artificial intelligence (AI) is expected to revolutionize the way we interact with intelligent vehicles. AI algorithms can be used to analyze vast amounts of data collected by intelligent vehicles and provide insights and recommendations to drivers. These insights can range from simple recommendations, such as the optimal speed to maintain to reach a destination, to more complex recommendations, such as the safest route to take during adverse weather conditions.

Thirdly, the future of cloud computing in intelligent vehicles is likely to see an increased focus on cybersecurity. As intelligent vehicles become more connected and reliant on cloud services, they become more vulnerable to cyber threats. To address these threats, manufacturers are expected to invest heavily in cybersecurity measures, such as encryption, authentication, and intrusion detection systems. Cloud service providers are also likely to offer specialized cybersecurity services to protect the data and systems of intelligent vehicles.

Finally, the future of cloud computing in intelligent vehicles is likely to see increased collaboration between manufacturers, cloud service providers, and other stakeholders in the automotive industry. Manufacturers are expected to partner with cloud service providers to develop customized cloud solutions that meet the unique needs of their vehicles. Cloud service providers are also likely to collaborate with other stakeholders in the automotive industry, such as road infrastructure providers, to provide integrated services that enhance the driving experience.

Cloud computing has the potential to transform the future of intelligent vehicles. The integration of cloud computing with AI, increased cybersecurity, the development of autonomous vehicles, and increased collaboration between stakeholders are some of the exciting developments on the horizon. As the use of cloud computing in intelligent vehicles continues to evolve, it is essential to address the limitations and challenges associated with this technology to ensure safe and efficient operation.

References

- [1] R. Li, C. Huang, Y. Zhou, Y. Chang, and Y. Wang, "Research on lithium battery sorting method based on image adaptive recognition of feature points," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 4, p. 314, 2022.
- [2] Y. Zhang, J. Liu, M. Zhou, and H. Gao, "Position sensorless control system of SPMSM based on high frequency signal injection method with passive controller," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 1/2, p. 112, 2022.
- [3] M. Zhou, W. Liu, Y. Zhang, and J. Wang, "Research on energy management of hybrid power system in fuel cell vehicles," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 1/2, p. 134, 2022.
- [4] C. M. R. Charles and J. S. Savier, "An overview on hybrid energy storage systems for electric vehicles," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 1/2, p. 56, 2022.

- [5] D. Bruggner, A. Hegde, F. S. Acerbo, D. Gulati, and T. D. Son, "Model in the loop testing and validation of embedded autonomous driving algorithms," in 2021 IEEE Intelligent Vehicles Symposium (IV), Nagoya, Japan, 2021.
- [6] A. K. Venkitaraman and V. S. R. Kosuru, "Hybrid deep learning mechanism for charging control and management of Electric Vehicles," *European Journal of Electrical Engineering and Computer Science*, vol. 7, no. 1, pp. 38–46, Jan. 2023.
- [7] J. Tang, X. Zhao, and J. Zhang, "Optimal control for shift mechanism of a planetary twospeed transmission for electric vehicles," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 3, p. 231, 2022.
- [8] V. F. Yakovlev, "Early electric vehicle charging: a survey," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 3, p. 219, 2022.
- [9] V. S. Rahul, "Kosuru; Venkitaraman, AK Integrated framework to identify fault in human-machine interaction systems," *Int. Res. J. Mod. Eng. Technol. Sci*, 2022.
- [10] V. Bandari, "Optimizing IT Modernization through Cloud Migration: Strategies for a Secure, Efficient and Cost-Effective Transition," *Applied Research in Artificial Intelligence and Cloud Computing*, vol. 5, no. 1, pp. 66–83, 2022.
- [11] K. Zhou, Y. Liu, N. Jin, and D. Sun, "Research of electric vehicle on-board controller based on inverter time division multiplexing," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 1/2, p. 30, 2022.
- [12] V. Bandari, "Exploring the Transformational Potential of Emerging Technologies in Human Resource Analytics: A Comparative Study of the Applications of IoT, AI, and Cloud Computing," *Journal of Humanities and Applied Science Research*, vol. 2, no. 1, pp. 15–27, 2019.
- [13] P. S. R. Nayak and G. Peddanna, "Mutual inductance estimation between rectangular structures magnetic coils with various misalignments for wireless EV charger," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 3, p. 250, 2022.
- [14] A. Naderolasli, "Indirect self-tuning controller for a two degree of freedom tracker model," Int. J. Veh. Auton. Syst., vol. 16, no. 1, p. 15, 2021.
- [15] P. Patil, "Applications of Deep Learning in Traffic Management: A Review," *International Journal of Business Intelligence and Big Data Analytics*, vol. 5, no. 1, pp. 16–23, 2022.
- [16] Y. Zhou, Y. Wang, Y. Chang, C. Huang, and R. Li, "Research on lithium battery sorting method based on image adaptive recognition of feature points," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 4, p. 314, 2022.
- [17] M. Chen, Y. Ren, and M. Ou, "Adaptive robust path tracking control for autonomous vehicles considering multi-dimensional system uncertainty," *World Electric Veh. J.*, vol. 14, no. 1, p. 11, Jan. 2023.
- [18] V. Bandari, "The Impact of Artificial Intelligence on the Revenue Growth of Small Businesses in Developing Countries: An Empirical Study," *Reviews of Contemporary Business Analytics*, vol. 2, no. 1, pp. 33–44, 2019.
- [19] M. Aboutorabi Kashani, M. Abbasi, A. R. Mamdoohi, and G. Sierpiński, "The role of attitude, travel-related, and socioeconomic characteristics in modal shift to shared autonomous vehicles with ride sharing," *World Electric Veh. J.*, vol. 14, no. 1, p. 23, Jan. 2023.
- [20] V. Bandari, "BEYOND TECHNOLOGY: A HOLISTIC FRAMEWORK FOR SMART URBANIZATION IN DEVELOPING COUNTRIES," *Tensorgate Journal of Sustainable Technology and Infrastructure for Developing Countries*, vol. 5, no. 1, pp. 1–13, 2022.
- [21] V. S. R. Kosuru and A. K. Venkitaraman, "Evaluation of Safety Cases in The Domain of Automotive Engineering," *International Journal of Innovative Science and Research Technology*, vol. 7, no. 9, pp. 493–497, 2022.

- [22] Z. Yang, Y. Hu, and Y. Zhang, "Path-planning strategy for Lane changing based on adaptive-grid risk-fields of autonomous vehicles," *World Electric Veh. J.*, vol. 13, no. 10, p. 175, Sep. 2022.
- [23] X. Li, Q. Li, C. Yin, and J. Zhang, "Autonomous navigation technology for low-speed small unmanned vehicle: An overview," *World Electric Veh. J.*, vol. 13, no. 9, p. 165, Aug. 2022.
- [24] P. Patil, "A Review of Connected and Automated Vehicle Traffic Flow Models for Next-Generation Intelligent Transportation Systems," *Applied Research in Artificial Intelligence and Cloud Computing*, vol. 1, no. 1, pp. 10–22, 2018.
- [25] V. S. R. Kosuru and A. K. Venkitaraman, "Developing a deep Q-learning and neural network framework for trajectory planning," *European Journal of Engineering and Technology Research*, vol. 7, no. 6, pp. 148–157, Dec. 2022.
- [26] L. Kumar and N. A. Ravi, "Electric vehicle charging method and impact of charging and discharging on distribution system: a review," *Int. J. Electr. Hybrid Veh.*, vol. 14, no. 1/2, p. 87, 2022.
- [27] V. Bandari, "Predictive Analytics in Cloud Computing: An ARIMA Model Study on Performance Metrics," *Applied Research in Artificial Intelligence and Cloud Computing*, vol. 4, no. 1, pp. 1–18, 2021.
- [28] K. Moridpour, M. Masih Tehrani, and S. Shabzendehdar, "Developing a novel rear steering angle control strategy for a modern three-wheeler," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 56, 2021.
- [29] S. Shabzendehdar, M. M. Tehrani, and K. Moridpour, "Developing a novel rear steering angle control strategy for a modern three-wheeler," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 56, 2021.
- [30] P. Patil, "Sustainable Transportation Planning: Strategies for Reducing Greenhouse Gas Emissions in Urban Areas," *Empirical Quests for Management Essences*, vol. 1, no. 1, pp. 116–129, 2021.
- [31] V. Bandari, "Cloud Workload Forecasting with Holt-Winters, State Space Model, and GRU," *Journal of Artificial Intelligence and Machine Learning in Management*, vol. 4, no. 1, pp. 27–41, 2020.
- [32] V. Bandari, "Proactive Fault Tolerance Through Cloud Failure Prediction Using Machine Learning," *ResearchBerg Review of Science and Technology*, vol. 3, no. 1, pp. 51–65, 2020.
- [33] R. Utriainen and M. Pöllänen, "The safety potential of automatic emergency braking and adaptive cruise control and actions to improve the potential," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 1, 2021.
- [34] A. Kusari *et al.*, "Enhancing SUMO simulator for simulation based testing and validation of autonomous vehicles," in 2022 IEEE Intelligent Vehicles Symposium (IV), Aachen, Germany, 2022.
- [35] V. Bandari, "The Adoption Of Next Generation Computing Architectures: A Meta Learning On The Adoption Of Fog, Mobile Edge, Serverless, And SoftwareDefined Computing," *ssraml*, vol. 2, no. 2, pp. 1–15, 2019.
- [36] P. Patil, "A Comparative Study of Different Time Series Forecasting Methods for Predicting Traffic Flow and Congestion Levels in Urban Networks," *International Journal of Information and Cybersecurity*, vol. 6, no. 1, pp. 1–20, 2022.
- [37] A. K. Venkitaraman and V. S. R. Kosuru, "A review on autonomous electric vehicle communication networks-progress, methods and challenges," *World J. Adv. Res. Rev.*, vol. 16, no. 3, pp. 013–024, Dec. 2022.
- [38] R. Srikanth and M. Venkatesan, "Design and modelling of hybrid fuel cell and solarbased electric vehicle," *Int. J. Veh. Auton. Syst.*, vol. 15, no. 3/4, p. 225, 2020.
- [39] H. Kaja, Survivable and Reliable Design of Cellular and Vehicular Networks for Safety Applications. University of Missouri-Kansas City, 2021.



- [40] A. Naderolasli, "Indirect self-tuning controller for a two degree of freedom tracker model," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 15, 2021.
- [41] R. Utriainen and M. Pöllänen, "The safety potential of automatic emergency braking and adaptive cruise control and actions to improve the potential," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 1, 2021.
- [42] H. Kaja and C. Beard, "A Multi-Layered Reliability Approach in Vehicular Ad-Hoc Networks," *International Journal of Interdisciplinary Telecommunications and Networking (IJITN)*, vol. 12, no. 4, pp. 132–140, 2020.
- [43] H. Kaja, R. A. Paropkari, C. Beard, and A. Van De Liefvoort, "Survivability and disaster recovery modeling of cellular networks using matrix exponential distributions," *IEEE Trans. Netw. Serv. Manage.*, vol. 18, no. 3, pp. 2812–2824, 2021.
- [44] M. C. Mlati and Z. Wang, "Unmanned ground vehicles: adaptive control system for realtime rollover prevention," Int. J. Veh. Auton. Syst., vol. 16, no. 1, p. 81, 2021.
- [45] B. Arifin, B. Y. Suprapto, S. A. D. Prasetyowati, and Z. Nawawi, "Steering control in electric power steering autonomous vehicle using type-2 fuzzy logic control and PI control," *World Electric Veh. J.*, vol. 13, no. 3, p. 53, Mar. 2022.
- [46] P. Patil, "The Future of Electric Vehicles: A Comprehensive Review of Technological Advancements, Market Trends, and Environmental Impacts," *Journal of Artificial Intelligence and Machine Learning in Management*, vol. 4, no. 1, pp. 56–68, 2020.
- [47] B. Kim, PhD students, Autonomous Vehicle & Intelligent Robotics Program, Hongik University, Seoul, Korea (bongsai@mail.hongik.ac.kr), S. Cho, and H. Moon, "Slip detection and control algorithm to improve path tracking performance of four-wheel independently actuated farming platform," *J. Korea Robot. Soc.*, vol. 15, no. 3, pp. 221– 232, Jul. 2020.
- [48] S. Ge *et al.*, "Making standards for smart mining operations: Intelligent vehicles for autonomous mining transportation," *IEEE Trans. Intell. Veh.*, vol. 7, no. 3, pp. 413–416, Sep. 2022.
- [49] V. Bandari, "Integrating DevOps with Existing Healthcare IT Infrastructure and Processes: Challenges and Key Considerations," *Empirical Quests for Management Essences*, vol. 2, no. 4, pp. 46–60, 2018.
- [50] P. Patil, "Machine Learning for Traffic Management in Large-Scale Urban Networks: A Review," Sage Science Review of Applied Machine Learning, vol. 2, no. 2, pp. 24–36, 2019.
- [51] A. Rizzo, F. Aioun, A. Benine Neto, N. Monot, and X. Moreau, "Automated vehicle lateral guidance using multi-PID steering control and look-ahead point reference," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 38, 2021.
- [52] M. Zhou, W. Liu, Y. Zhang, and J. Fu, "Transient power smoothing control strategy for battery of pure electric bus," Int. J. Electr. Hybrid Veh., vol. 14, no. 1/2, p. 150, 2022.
- [53] N. Monot, X. Moreau, A. B. Neto, A. Rizzo, and F. Aioun, "Automated vehicle lateral guidance using multi-PID steering control and look-ahead point reference," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 38, 2021.
- [54] Z. Wang and M. C. Mlati, "Unmanned ground vehicles: adaptive control system for realtime rollover prevention," *Int. J. Veh. Auton. Syst.*, vol. 16, no. 1, p. 81, 2021.
- [55] Y.-S. Baek *et al.*, "A study of hazard analysis and monitoring concepts of autonomous vehicles based on V2V communication system at non-signalized intersections," *J. Korea Inst. Intell. Transp. Syst.*, vol. 19, no. 6, pp. 222–234, Dec. 2020.
- [56] P. Patil, "Innovations in Electric Vehicle Technology: A Review of Emerging Trends and Their Potential Impacts on Transportation and Society," *Reviews of Contemporary Business Analytics*, vol. 4, no. 1, pp. 1–13, 2021.
- [57] V. Bandari, "A Comprehensive Review of AI Applications in Automated Container Orchestration, Predictive Maintenance, Security and Compliance, Resource

Optimization, and Continuous Deployment and Testing," *International Journal of Intelligent Automation and Computing*, vol. 4, no. 1, pp. 1–19, 2021.

- [58] D. S. N. A. B. Ab Ahmad Zulkipli, S. Perumal, and M. Tabassum, "Development of a low-cost smart vehicle start up and tracking system using Android and Arduino," *Int. J. Veh. Auton. Syst.*, vol. 15, no. 3/4, p. 271, 2020.
- [59] P. Grasso, Autonomous Vehicles and Artificial Intelligence Laboratory Research Institute for Future Transport and Cities, Coventry University, M. Innocente, and Autonomous Vehicles and Artificial Intelligence Laboratory Research Institute for Future Transport and Cities, Coventry University, "Debiasing of position estimations of UWB-based TDoA indoor positioning system," in UK-RAS Conference for PhD and Early Career Researchers Proceedings, 2020.
- [60] P. Patil, "Electric Vehicle Charging Infrastructure: Current Status, Challenges, and Future Developments," *International Journal of Intelligent Automation and Computing*, vol. 2, no. 1, pp. 1–12, 2018.
- [61] V. S. R. Kosuru and A. K. Venkitaraman, "CONCEPTUAL DESIGN PHASE OF FMEA PROCESS FOR AUTOMOTIVE ELECTRONIC CONTROL UNITS," *International Research Journal of Modernization in Engineering Technology and Science*, vol. 4, no. 9, pp. 1474–1480, 2022.
- [62] V. Bandari, "Enterprise Data Security Measures: A Comparative Review of Effectiveness and Risks Across Different Industries and Organization Types," *International Journal of Business Intelligence and Big Data Analytics*, vol. 6, no. 1, pp. 1–11, 2023.
- [63] T. A. A. Victoire, F. T. Josh, M. C. Joseph, and J. J. Joseph, "Dynamic performance analysis of electrified propulsion system in electric vehicle," *Int. J. Veh. Auton. Syst.*, vol. 15, no. 1, p. 26, 2020.
- [64] P. Patil, "INTEGRATING ACTIVE TRANSPORTATION INTO TRANSPORTATION PLANNING IN DEVELOPING COUNTRIES: CHALLENGES AND BEST PRACTICES," *Tensorgate Journal of Sustainable Technology and Infrastructure for Developing Countries*, vol. 1, no. 1, pp. 1–15, 2019.
- [65] V. Bandari, "Impact of Data Democratization and Data Literacy on Employee Productivity," *Sage Science Review of Educational Technology*, vol. 3, no. 1, pp. 37–48, 2020.
- [66] P. Patil, "An Empirical Study of the Factors Influencing the Adoption of Electric Vehicles," *Contemporary Issues in Behavioral and Social Sciences*, vol. 4, no. 1, pp. 1– 13, 2020.
- [67] N. A. Anbu, A. K. Pinagapani, G. Mani, and K. R. Chandran, "Improved vehicle navigation using sensor fusion of inertial, odometeric sensors with global positioning system," *Int. J. Veh. Auton. Syst.*, vol. 15, no. 3/4, p. 307, 2020.
- [68] C. R. Munigety, "Motion planning methods for autonomous vehicles in disordered traffic systems: a comparative analysis and future research directions," *Int. J. Veh. Auton. Syst.*, vol. 15, no. 2, p. 152, 2020.
- [69] S. Yang, Y. Chen, R. Shi, R. Wang, Y. Cao, and J. Lu, "A survey of intelligent tires for tire-road interaction recognition toward autonomous vehicles," *IEEE Trans. Intell. Veh.*, vol. 7, no. 3, pp. 520–532, Sep. 2022.
- [70] X. Zhang, Y. Jiang, Y. Lu, and X. Xu, "Receding-horizon reinforcement learning approach for kinodynamic motion planning of autonomous vehicles," *IEEE Trans. Intell. Veh.*, vol. 7, no. 3, pp. 556–568, Sep. 2022.
- [71] X. Hu, N. K. Giang, J. Shen, V. C. M. Leung, and X. Li, "Towards Mobility-as-a-Service to Promote Smart Transportation," in 2015 IEEE 82nd Vehicular Technology Conference (VTC2015-Fall), 2015, pp. 1–5.